

# On Dynamic Resource Management Mechanism using Control Theoretic Approach for Wide-Area Grid Computing

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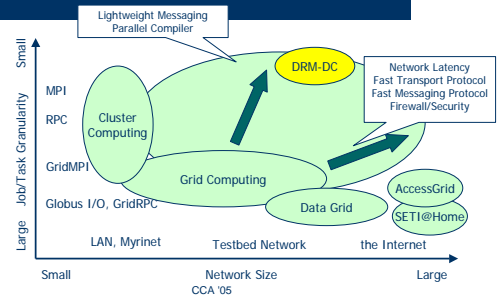
## Background

- Emergence of Grid computing
  - Integrate **geographically distributed** resources
  - Enable large-scale scientific computations
- Problems in wide-area Grid computing
  - **Variation in the amount of available resources**
    - Resources are shared by multiple users
    - e.g., computing resources, network, disk space
  - **Transfer delay** between sites is non-negligible
    - Round-trip time might be > 100ms
- Dynamic resource management is required

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## Grid Computing: Current and Future



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## Resource Management in Grid Computing



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## GRAM (Grid Resource Allocation and Management)

- A resource management component of Globus toolkit
- GRAM building blocks
  - Client
    - Create job, and ask gatekeeper for its execution
  - Gatekeeper
    - Authenticate user, and create job manager
  - Job manager
    - Assign job to local resource manager
  - Local resource manager
    - Execute job using site's available resource

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## Requirements for Resource Management in Grid Computing

- Objectives
  - Adjust the amount of jobs injected into a site...
    - According to the amount of available resources
- Desired characteristics
  - Steady-state performance
    - High resource utilization, fast job execution
  - Transient-state performance
    - Fast convergence
  - Stability, robustness, flexibility...

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## Problems in Wide-Area Grid Computing

- Variation in the amount of available resources
  - Simple open-loop control is insufficient
  - Closed-loop control using feedback information is indispensable
- Transfer delay between sites is non-negligible
  - Difficult to realize stability and fast convergence
  - Feedback delay must be taken account of

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## Research Objectives

- Propose dynamic resource management mechanism
  - DRM-DC (Dynamic Resource Management with Delay Compensator)
  - Feedback-based control with a delay compensator
  - Realize high steady-/transient-state performance
- Performance evaluation of DRM-DC
  - Implement DRM-DC in Simgrid simulator
  - Comparison of DRM-DC with PI controller
  - Show DRM-DC's effectiveness in WAN environment

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## Modeling Assumptions

- Parameter-sweep applications
  - Job manager always has jobs to execute
    - Job = multiple tasks
  - Task granularity is small
    - i.e., task execution time  $\ll$  transfer delay
- Transfer delay is constant
  - Network between sites is not heavily congested

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## Modeling Site (Plant)

- Can be modeled as a single queue
  - Site processes assigned tasks one by one
    1. Receive tasks from job manager
    2. Queue them in buffer of local resource manager
    3. Process tasks in the buffer one by one
- Continuous-time system model
  - Input  $u(t)$ : task injection rate from job manager
  - Output  $x(t)$ : the number of tasks in the buffer

$$\dot{x}(t) = \left[ \int_0^t (u(v) - \tau(x(v)) - \rho(x(v))dv) \right]^+$$

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## Modeling Job Manager (Controller)

- Can be modeled as a controller
  - Job manager assigns tasks to each site
    1. Receive feedback information from sites
    2. Adjust the amount of task assignments to sites
- Continuous-time system model
  - Input  $x(t)$ : the number of waiting tasks in site
  - Output  $u(t)$ : task injection rate to site

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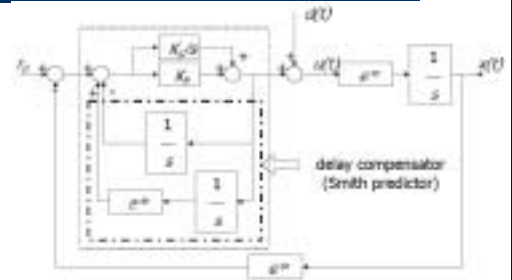
## Dynamic Resource Management Mechanism DRM-DC

- DRM-DC (Dynamic Resource Management with Delay Compensator)
- Controller running on job manager
  - Input: the number of tasks waiting in site
  - Output: task injection rate to site
- DRM-DC control objective
  - Keep the number of tasks in the buffer at target level
    - Avoid overload and realize high utilization
- PI (Proportional Integral) controller with a delay compensator (Smith Predictor)

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## Block Diagram of DRM-DC



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## Performance Evaluation

- Modified a discrete-time simulator Simgrid
  - Implement discrete-time version of DRM-DC (controls at every constant interval  $T$ )
- Simulation conditions
  - Parameter-sweep applications
  - Number of sites: 10
  - Network: LAN (1 [ms]), WAN (100 [ms])
- Performance metrics
  - Queue dynamics (i.e., the number of tasks in buffer)

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## Simulation Scenario: Parameter Configuration

- Simulation scenarios
  1. Varying amount of available resources
  2. Varying transfer delay between job manager and site

	LAN-S2	LAN-S20	WAN-S2	WAN-S20
task size $S$ [M]	2	20	2	20
transfer delay $\tau$ [ms]	1.0	1.0	100.0	100.0
control interval $T$ [ms]	2.0	20.0	2.0	20.0
target queue length $n_t$	200	20	200	20

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## Simulation Result (Queue Dynamics for Varying Available Resources)

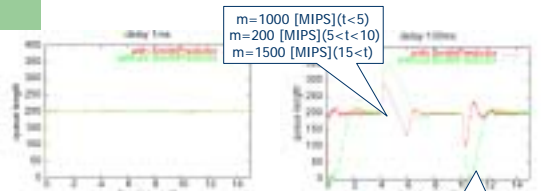


Fig. 2. Time 1000 [MIPS] (t<5) m=200 [MIPS] (5<t<10) m=1500 [MIPS] (15<t)

Fig. 3. Time 1000 [MIPS] (t<5) m=200 [MIPS] (5<t<10) m=1500 [MIPS] (15<t)

DRM-DC shows better utilization, faster convergence

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## Simulation Result (Rise Time, Overshoot, Settling Time)

	$\tau$ [ms]	$T$ [ms]	rise time [s]	overshoot [%]	settling time [s]
LAN-S2 DRM-DC	1.0	2	0.016	0.5	0.012
LAN-S2 PI	1.0	2	0.016	0.5	0.008
LAN-S20 DRM-DC	1.0	20	0.4	5	0.8
LAN-S20 PI	1.0	20	0.8	5	0.8
WAN-S2 DRM-DC	100.0	2	0.23	46	0.11
WAN-S2 PI	100.0	2	0.6	79	0.7
WAN-S20 DRM-DC	100.0	20	0.19	25	0.3
WAN-S20 PI	100.0	20	1.62	95	0.6

DRM-DC shows significantly shorter rise time/settling time

DRM-DC shows smaller overshoot

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## Conclusion and Future Work

- Proposed dynamic resources management mechanism
  - Designed for **wide-area Grid computing**
  - Utilize a **delay compensator** (Smith predictor)
- Verified its effectiveness by simulation
  - Realize **high steady-/transient-state performance**
  - Effective in **WAN environment** with a large delay
- Future work
  - Improvement of stability, robustness, and flexibility
  - Implementation in Globus toolkit